

# SE Course: Stochastic Analysis for Engineers

<http://www.cs.aue.auc.dk/~yang/course/stoc04.htm>

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## MM2: Discrete Linear Process Models

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### 1 Reading

Chapt 5, pp.250-275 of K. Sam Shanmugan and Arthur M. Breipohl: "Random Signals - Detection, Estimation and Data Analysis", John Wiley Sons, Inc., 1988.

### 2 Content

- Moving Average (MA) models;
- Autoregressive (AR) models;
- Autoregressive Moving Average (ARMA) models.

### 3 Exercise

1. (Problem 4.14 in Textbook, page 246. )

Assume the input to a LTI system is a zero-mean Gaussian random process with property:

$$S_{XX}(f) = \eta/2$$

and the impulse response of the considered system is

$$h(t) = \begin{cases} \exp(-t), & t \geq 0 \\ 0, & \text{others} \end{cases}$$

- (a) Find  $S_{YY}(f)$ , where  $Y(t)$  is the output;
- (b) Find  $E\{Y^2(t)\}$ .

2. (Problem 5.3, 5.4 in Textbook, page 333. )

An AR process  $Y(n)$  is expressed as

$$Y(n) = \frac{1}{2}Y(n-1) + Z(n), \quad n = 1, 2, \dots$$

where  $Z(n)$  is a stationary white Gaussian noise with zero mean and  $\delta_Z^2 = 1$ .  $Y(0)$  is a Gaussian random variable and independent of  $Z(n)$ .

- (a) Find the mean and variance of  $Y(0)$  in order for the process to be stationary;
- (b) Assume the process is stationary, find, for the sequence  $Y(n)$ , (i)  $\mu_Y$ ; (ii)  $\delta_Y^2$ ; (iii)  $R_{YY}(k)$ ; (iv)  $r_{YY}(k)$ ; (v)  $S_{YY}(f)$ .

3. Prepare your self-study materials and presentation.